# A General Valuation Framework for SABR and Stochastic Local Volatility Models 

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## Overview

- Stochastic local volatility (SLV) models, including:
- SABR (variants: shifted, lambda, Heston, etc.)
- Quadratic SLV (Lipton), root quadratic SLV
- Includes pure stochastic volatility (SV) as special case:
- Heston, Jacobi, Hull-White, 3/2, Stein-Stein, 4/2, Scott, $\alpha$-Hypergeometric, etc.
- Includes mean-reverting Commodity models:
- Ornstein-Uhlenbeck with SV, mean-reverting SABR, etc.
- Contracts: European, Bermudan/American, Barrier, Asian, Parisian/Occupation time, Lookback


## Stochastic Local Volatility

- Local volatility (Dupire $(1994)^{4}$, Derman et al $\left.(1996)^{5}\right)$, for "perfect calibration":

$$
L V: \quad d S_{t}=S_{t} \mu d t+\sigma_{L V}\left(S_{t}, t\right) S_{t} d W_{t}
$$

- Stochastic volatility for realistic surface dynamics:

$$
S V:\left\{\begin{array}{l}
d S_{t}=S_{t} \mu d t+m\left(v_{t}\right) S_{t} d W_{t}^{(1)} \\
d v_{t}=\mu\left(v_{t}\right) d t+\sigma\left(v_{t}\right) d W_{t}^{(2)}
\end{array}\right.
$$

- Stochastic local volatility to unite the two:

$$
S L V:\left\{\begin{array}{l}
d S_{t}=\omega\left(S_{t}, v_{t}\right) d t+m\left(v_{t}\right) \Gamma\left(S_{t}\right) d W_{t}^{(1)} \\
d v_{t}=\mu\left(v_{t}\right) d t+\sigma\left(v_{t}\right) d W_{t}^{(2)}
\end{array}\right.
$$

${ }^{4}$ Dupire, B. (1994). Pricing with a Smile. Risk Magazine.
${ }^{5}$ Derman, E., Kani, I., and Chriss, N. (1996). Implied trinomial tress of the volatility smile. The Journal of Derivatives, 3(4), 7-22.

## Applicable SLV Dynamics

| SABR | $d S_{t}=v_{t} S_{t}^{\beta} d W_{t}^{(1)}$ | $\beta \in[0,1)$ |
| :---: | :---: | :---: |
| (Hagan et al. (2002)) | $d v_{t}=\alpha v_{t} d W_{t}^{(2)}$ | $\alpha, v_{0}>0$ |
| $\lambda-$ SABR | $d S_{t}=v_{t} S_{t}^{\beta} d W_{t}^{(1)}$ | $\beta \in[0,1)$ |
| (Henry-Labodere (2005)) | $d v_{t}=\lambda\left(\theta-v_{t}\right) d t+\alpha v_{t} d W_{t}^{(2)}$ | $\lambda, \theta, \alpha, v_{0}>0$ |
| Shifted SABR | $d S_{t}=v_{t}\left(S_{t}+s\right)^{\beta} d W_{t}^{(1)}$ | $\beta \in[0,1)$ |
| (Antonov et al. (2015)) | $d v_{t}=\alpha v_{t} d W_{t}^{(2)}$ | $s, \alpha, v_{0}>0$ |
| Heston-SABR | $d S_{t}=r S_{t} d t+\sqrt{v_{t}} S_{t}^{\beta} d W_{t}^{(1)}$ | $r \in \mathbb{R}, \beta \in[0,1)$ |
| (Van Der Stoep et al. (2014)) | $d v_{t}=\eta\left(\theta-v_{t}\right) d t+\alpha \sqrt{v_{t}} d W_{t}^{(2)}$ | $\eta, \theta, \alpha, v_{0}>0$ |
| Quadratic SLV | $d S_{t}=r S_{t} d t+\sqrt{v_{t}}\left(a S_{t}^{2}+b S_{t}+c\right) d W_{t}^{(1)}$ | $r \in \mathbb{R}, \beta \in[0,1)$ |
| (Lipton (2002)) | $d v_{t}=\eta\left(\theta-v_{t}\right) d t+\alpha \sqrt{v_{t}} d W_{t}^{(2)}$ | $a, \eta, \theta, \alpha, v_{0}>0,4 a c>b^{2}$ |
| Exponential SLV | $d S_{t}=r S_{t} d t+m\left(v_{t}\right)\left(v_{L}+\theta e x p\left(-\lambda S_{t}\right)\right) d W_{t}^{(1)}$ | $r \in \mathbb{R}, \lambda, v_{L} \geq 0$ |
|  | $d v_{t}=\mu\left(v_{t}\right) d t+\sigma\left(v_{t}\right) d W_{t}^{(2)}$ | $v_{L}+\theta \geq 0$ |
| Root-Quadratic SLV | $d S_{t}=r S_{t} d t+m\left(v_{t}\right) \sqrt{a S_{t}^{2}+b S_{t}+c} d W_{t}^{(1)}$ | $r \in \mathbb{R}$ |
|  | $d v_{t}=\mu\left(v_{t}\right) d t+\sigma\left(v_{t}\right) d W_{t}^{(2)}$ | $a>0, c \geq 0$ |
| Tan-Hyp SLV | $d S_{t}=r S_{t} d t+m\left(v_{t}\right) \tanh \left(\beta S_{t}\right) d W_{t}^{(1)}$ | $r \in \mathbb{R}$ |
|  | $d v_{t}=\mu\left(v_{t}\right) d t+\sigma\left(v_{t}\right) d W_{t}^{(2)}$ | $\beta \geq 0$ |
| Mean-reverting-SABR | $d S_{t}=\kappa\left(\zeta-S_{t}\right) d t+m\left(v_{t}\right) S_{t}^{\beta} d W_{t}^{(1)}$ | $r \in \mathbb{R}, \beta \in[0,1)$ |
|  | $d v_{t}=\mu\left(v_{t}\right) d t+\sigma\left(v_{t}\right) d W_{t}^{(2)}$ | $\kappa, \zeta, v_{0}>0$ |
| 4/2-SABR | $d S_{t}=r S_{t} d t+S_{t}^{\beta}\left[a \sqrt{v_{t}}+b / \sqrt{v_{t}}\right] d W_{t}^{(1)}$ | $r \in \mathbb{R}, \beta \in[0,1)$ |
| $d v_{t}=\eta\left(\theta-v_{t}\right) d t+\alpha \sqrt{v_{t} d W_{t}^{(2)}}$ | $a, b, \eta, \theta, \alpha, v_{0}>0$ |  |

Table: Some stochastic local volatility models

## Applicable SV Dynamics

| Heston <br> (Heston 1993) | $\begin{gathered} m(v)=\sqrt{v}, \quad d v_{t}=\eta\left(\theta-v_{t}\right) d t+\sigma_{v} \sqrt{v_{t}} d W_{t}^{(2)} \\ f(v)=v / \sigma_{v}, \quad h(v)=\eta(\theta-v) / \sigma_{v} \end{gathered}$ |
| :---: | :---: |
| $\begin{gathered} 4 / 2 \\ (\text { Grasselli 2016) } \end{gathered}$ | $\begin{aligned} & m(v)=a \sqrt{v}+b / \sqrt{v}, \quad d v_{t}=\eta\left(\theta-v_{t}\right) d t+\sigma_{v} \sqrt{v_{t}} d W_{t}^{(2)} \\ & f(v)=\frac{(a v+b \log (v))}{\sigma_{v}}, \quad h(v)=\frac{\eta(a \theta-b)}{\sigma_{v}}-\frac{a \eta v}{\sigma_{v}}+\left(\frac{\eta \theta b}{\sigma_{v}}-\frac{b \sigma_{v}}{2}\right) \frac{1}{v} \end{aligned}$ |
| Stein-Stein (Stein-Stein 1991) | $\begin{aligned} & m(v)=v, \quad d v_{t}=\eta\left(\theta-v_{t}\right) d t+\sigma_{v} d W_{t}^{(2)} \\ & f(v)=\frac{v^{2}}{2 \sigma_{v}}, \quad h(v)=\frac{\sigma_{v}}{2}+\frac{\eta \theta_{v}}{\sigma_{v}}-\frac{\eta v^{2}}{\sigma_{v}} \end{aligned}$ |
| $\begin{gathered} 3 / 2 \\ (\text { Lewis } 2000 \text { ) } \end{gathered}$ | $\begin{gathered} m(v)=1 / \sqrt{v}, \quad d \widehat{v}_{t}=\widehat{\eta}\left[\widehat{\theta}-\widehat{v}_{t}\right] d t+\widehat{\sigma}_{v} \sqrt{\widehat{v}_{t}} d W_{t}^{(2)} \\ f(v)=\frac{\log (v)}{\widehat{\sigma}_{v}}, \quad h(v)=\left(\frac{\widehat{\hat{\theta}}}{\hat{\sigma}_{v}}-\frac{\widehat{\sigma}_{v}}{2}\right) \frac{1}{v}-\frac{\widehat{\sigma_{v}}}{\sigma_{v}} \end{gathered}$ |
| Hull-White (Hull-White 1987) | $\begin{gathered} m(v)=\sqrt{v}, \quad d v_{t}=a_{v} v_{t} d t+\sigma_{v} v_{t} d W_{t}^{(2)} \\ f(v)=\frac{2 \sqrt{v}}{\sigma_{v}}, \quad h(v)=\left(\frac{a_{v}}{\sigma_{v}}-\frac{\sigma_{v}}{4}\right) \sqrt{v} \end{gathered}$ |
| Scott (Scott 1987) | $\begin{gathered} m(v)=\exp (v), \quad d v_{t}=\eta\left(\theta-v_{t}\right) d t+\sigma_{v} d W_{t}^{(2)} \\ f(v)=\frac{e^{v}}{\sigma_{v}}, \quad h(v)=e^{v}\left(\frac{\eta \theta}{\sigma_{v}}+\frac{\sigma_{v}}{2}-\frac{\eta v}{\sigma_{v}}\right) \end{gathered}$ |
| $\alpha$-Hyper <br> (Da Fonseca \& Martini 2016) | $\begin{gathered} m(v)=\exp (v), \quad d v_{t}=\left(\eta-\theta \exp \left(a_{v} v_{t}\right)\right) d t+\sigma_{v} d W_{t}^{(2)} \\ f(v)=\frac{e^{v}}{\sigma_{v}}, \quad h(v)=e^{v}\left(\frac{\eta}{\sigma_{v}}+\frac{\sigma_{v}}{2}\right)-\frac{\theta}{\sigma_{v}} e^{\left(a_{v}+1\right) v} \end{gathered}$ |
| Jacobi (Ackerer et al. 2016) | $\begin{gathered} d v_{t}=\kappa\left(\theta-v_{t}\right) d t+\alpha \sqrt{Q\left(v_{t}\right)} d W_{t}^{(2)} \\ \text { (see paper) } \end{gathered}$ |

Table: Dynamics and variance transforms for some stochastic volatility models.

## Technical Assumptions

- Assumption 1. Let $P_{t} \Phi(S, v)=\mathbb{E}\left[\Phi\left(S_{t}, v_{t}\right) \mid S_{0}=S, v_{0}=v\right]$, and for any $\Phi \in C_{0}([0, \infty) \times[0, \infty))$, we assume that $\left(S_{t}, v_{t}\right)$ is a Feller process, i.e.
- $P_{t} \Phi \in C_{0}([0, \infty) \times[0, \infty))$ for any $t \geq 0$
- $\lim _{t \rightarrow 0} P_{t} \Phi(S, v)=\Phi(S, v)$ for any $(S, v) \in[0, \infty) \times[0, \infty)$.
- The Feller property guarantees that there exists a version of the process $\left(S_{t}, v_{t}\right)$ with cádlág paths satisfying the strong Markov property.
- The family of $P_{t} \Phi(S, v)$ is determined by its infinitestimal generator $\mathcal{L}^{S}$ :

$$
\begin{equation*}
\mathcal{L}^{S} \Phi(S, v)=\lim _{t \rightarrow 0+} \frac{\left(P_{t} \Phi-\Phi\right)(S, v)}{t} \tag{1}
\end{equation*}
$$

- Assumption 2. We assume that

$$
\begin{equation*}
\lim _{(S, v) \rightarrow(0,0)} \mathcal{L}^{S} \Phi(S, v)=0 \tag{2}
\end{equation*}
$$

## SLV Methodology Outline

$$
S L V:\left\{\begin{array}{l}
d S_{t}=\omega\left(S_{t}, v_{t}\right) d t+m\left(v_{t}\right) \Gamma\left(S_{t}\right) d W_{t}^{(1)} \\
d v_{t}=\mu\left(v_{t}\right) d t+\sigma\left(v_{t}\right) d W_{t}^{(2)}
\end{array}\right.
$$

1. Transformation: $\left(S_{t}, v_{t}\right) \rightarrow\left(X_{t}, v_{t}\right)$, to decouple the local and stochastic volatility term $m\left(v_{t}\right) \Gamma\left(S_{t}\right)$
2. First layer approximation: $\left(\tilde{X}_{t}, v_{\alpha(t)}\right)$, where $v_{\alpha(t)}$ is a locally consistent CTMC approximation to $v_{t}$.
3. Second layer approximation: $\left(\tilde{X}_{t}^{(N)}, v_{\alpha(t)}\right)$, a nonlinear Regime Switching CTMC
4. Dimension Reduction: $\left(\tilde{X}_{t}^{(N)}, v_{\alpha(t)}\right) \rightarrow Y_{t}$, a one-dimensional CTMC
5. Pricing in the space of $Y_{t}$

## Transformed Process

- First apply standard Cholesky decomposition

$$
\begin{aligned}
d S_{t} & =\omega\left(S_{t}, v_{t}\right) d t+m\left(v_{t}\right) \Gamma\left(S_{t}\right) d W_{t}^{(1)} \\
& =\omega\left(S_{t}, v_{t}\right) d t+m\left(v_{t}\right) \Gamma\left(S_{t}\right)\left(\rho d W_{t}^{(2)}+\sqrt{1-\rho^{2}} d W_{t}^{(*)}\right)
\end{aligned}
$$

which contains two (independent) Brownian motions

- Goal is to obtain an auxiliary process of the form:

$$
d F\left(S_{t}, v_{t}\right)=F^{1}\left(S_{t}, v_{t}\right) d t+F^{2}\left(S_{t}, v_{t}\right) d W_{t}^{(*)}
$$

driven by a single Brownian motion

- Such a process is amenable to a regime switching approximation


## Transformed Process

Recall: $\quad d S_{t}=\omega\left(S_{t}, v_{t}\right) d t+m\left(v_{t}\right) \Gamma\left(S_{t}\right) d W_{t}^{(1)}$
Lemma
Define the functions $g(x):=\int_{.}^{x} \frac{1}{\Gamma(u)} d u$ and $f(x):=\int_{.}^{x} \frac{m(u)}{\sigma(u)} d u$.
Then we have

$$
\left\{\begin{array}{l}
d\left(g\left(S_{t}\right)-\rho f\left(v_{t}\right)\right)=\left(\frac{\omega\left(S_{t}, v_{t}\right)}{\Gamma\left(S_{t}\right)}-\frac{\Gamma^{\prime}\left(S_{t}\right)}{2} m^{2}\left(v_{t}\right)-\rho h\left(v_{t}\right)\right) d t \\
d v_{t}=\mu\left(v_{t}\right) d t+\sigma\left(v_{t}\right) d W_{t}^{(2)},
\end{array}\right.
$$

where $W_{t}^{*}$ and $W_{t}^{(2)}$ are two independent Brownian motions, and

$$
h\left(v_{t}\right)=\mu\left(v_{t}\right) \frac{m\left(v_{t}\right)}{\sigma\left(v_{t}\right)}+\frac{1}{2}\left(\sigma\left(v_{t}\right) m^{\prime}\left(v_{t}\right)-m\left(v_{t}\right)\right) .
$$

This defines the auxiliary process $X_{t}:=g\left(S_{t}\right)-\rho f\left(v_{t}\right)$.

## Markov Chain Review

- Consider a CTMC, $\alpha(t) \in \mathcal{M}:=\left\{1,2, \ldots, m_{0}\right\}$
- Transition density at time $t$ of $\alpha(t+\Delta t) \mid \alpha(s), 0 \leq s \leq t$, depends only on $\alpha(t)$
- Dynamics of $\alpha(t)$ captured by rate matrix $\boldsymbol{\Lambda}=\left[\lambda_{i j}\right]_{m_{0} \times m_{0}}$
- $\lambda_{i j}$ is transition rate from state $i$ to $j$, and $\lambda_{i i}=-\sum_{j \neq i} \lambda_{i j}$
- In particular, $\forall i \neq j$ :

$$
\mathbb{Q}\left(\alpha(t+\Delta t)=j \mid \alpha(t)=i, \alpha\left(t^{\prime}\right), 0 \leq t^{\prime} \leq t\right)=\lambda_{i j} \Delta t+o(\Delta t)
$$

- Closed-form probabilities in terms of matrix exponential:

$$
\mathbf{P}(\Delta t)=\exp (\boldsymbol{\Lambda} \cdot \Delta t):=\sum_{k=0}^{\infty} \frac{(\boldsymbol{\Lambda} \cdot \Delta t)^{k}}{k!}
$$

## First Layer Approximation: Variance CTMC Approximation

- Define $v_{\alpha(t)}$, a CTMC approximating $v_{t}$, by defining a rate matrix $\boldsymbol{\Lambda}=\left[\lambda_{i j}\right]_{m_{0} \times m_{0}}$ for $\alpha(t)$
- Local consistency: choose $\boldsymbol{\Lambda}$ so that first two moments of $d v_{t}$ and $d v_{\alpha(t)}$ match locally
- For example: uniform grid $v_{i}=v_{1}+\delta_{v}(i-1), i=1, \ldots, m_{0}$

$$
\lambda_{i j}= \begin{cases}\frac{-\mu\left(v_{i}\right)}{2 \delta_{v}}+\frac{\sigma^{2}\left(v_{i}\right)}{2 \delta_{v}^{2}}, & j=i-1, \\ -\frac{\sigma^{2}\left(v_{i}\right)}{\delta_{v}^{2}}, & j=i, \\ \frac{\mu\left(v_{i}\right)}{2 \delta_{v}}+\frac{\sigma^{2}\left(v_{i}\right)}{2 \delta_{v}^{2}}, & j=i+1\end{cases}
$$

- In practice, we apply the generator of Lo and Skindilias (2014), as in Kirkby et. al (2016) for pure SV, combined with nonuniform grid of Tavella and Randall (2000)


## Second Layer Approximation: Regime Switching CTMC

- In first stage, we approximated $v_{t}$ with $v_{\alpha(t)}$
- Process $\left(\tilde{X}_{t}, v_{\alpha(t)}\right)$ defines a nonlinear regime switching (RS) model, which maps to $\left(\tilde{S}_{t}, v_{\alpha(t)}\right)$
- Mapping is defined by

$$
\begin{gathered}
\tilde{X}_{t}:=g\left(\tilde{S}_{t}\right)-\rho f\left(v_{\alpha(t)}\right) \\
\tilde{S}_{t}=g^{-1}\left(\tilde{X}_{t}+\rho f\left(v_{\alpha(t)}\right)\right)
\end{gathered}
$$

- In particular, we have a new RS model for $\tilde{S}_{t}$,

$$
d \tilde{S}_{t}=\omega\left(\tilde{S}_{t}, v_{\alpha(t)}\right) d t+m\left(v_{\alpha(t)}\right) \Gamma\left(\tilde{S}_{t}\right) d W_{t}^{(1)}, \quad \tilde{S}_{0}=S_{0}
$$

## Second Layer Approximation: Regime Switching CTMC

- We focus on the dynamics of $\tilde{X}_{t}$, with solution:

$$
\tilde{X}_{t}=g\left(S_{0}\right)-\rho f\left(v_{0}\right)+\int_{0}^{t} \theta\left(\tilde{X}_{t}, v_{\alpha(t)}\right) d t+\sqrt{1-\rho^{2}} \int_{0}^{t} m\left(v_{\alpha(t)}\right) d W_{t}^{*}
$$

- For each fixed state $v_{\alpha(t)}$, this process is a (time-homogeneous) diffusion
- Hence, we apply a second layer CTMC, with generators $\boldsymbol{G}^{\prime}=\left[q_{i j}^{\prime}\right]_{N \times N}$, for $I=1, \ldots, m_{0}$ :

$$
q_{k j}^{\prime}= \begin{cases}\frac{-\theta\left(x_{k}, v_{l}\right)}{2 \delta_{x}}+\frac{\tilde{\sigma}^{2}\left(v_{i}\right)}{2 \delta_{x}^{2}}, & j=k-1, \\ -\frac{\tilde{\sigma}^{2}\left(v_{i}\right)}{\delta_{x}^{2}}, & j=k, \\ \frac{\theta\left(x_{x_{2}}, v_{1}\right)}{2 \delta_{x}}+\frac{\tilde{\sigma}^{2}\left(v_{i}\right)}{2 \delta_{x}^{2}}, & j=k+1\end{cases}
$$

where $\tilde{\sigma}\left(v_{l}\right):=\sqrt{1-\rho^{2}} m\left(v_{l}\right)$

- New process: $\left(\tilde{X}^{(N)}, v_{\alpha(t)}\right)$ is a RS-CTMC


## Relation to Infinitesimal Generator

- The infinitesimal generator of $\left(\tilde{X}^{(N)}, v_{\alpha(t)}\right)$ :

$$
\begin{aligned}
\mathcal{L}_{N}^{m_{0}} V\left(x_{k}, v_{l}\right) & =\sum_{j=1}^{N} g_{k j}^{\prime} V_{j}^{\prime}+\sum_{n=1}^{m_{0}} \lambda_{l n} V_{k}^{n} \\
& =\left(g_{k, k-1}^{\prime} V_{k-1}^{\prime}+g_{k k}^{\prime} V_{k}^{\prime}+g_{k, k+1}^{\prime} V_{k+1}^{\prime}\right) \\
& +\underbrace{\left(\lambda_{l, l-1} V_{k}^{\prime-1}+\lambda_{l /} V_{k}^{\prime}+\lambda_{l, l+1} V_{k}^{\prime+1}\right)}
\end{aligned}
$$

- Generator of $\left(X_{t}, v_{t}\right)$ given by

$$
\begin{aligned}
\mathcal{L} V(x, v) & =\frac{1}{2}\left(1-\rho^{2}\right)[m(v)]^{2} \frac{\partial^{2} V}{\partial x^{2}}+\theta(x, v) \frac{\partial V}{\partial x} \\
& +\underbrace{\frac{1}{2} \sigma^{2}(v) \frac{\partial^{2} V}{\partial v^{2}}+\mu(v) \frac{\partial V}{\partial v}} .
\end{aligned}
$$

## Relation to Infinitesimal Generator

- Comparing, for example, the underlined terms:

$$
\begin{aligned}
& \lambda_{I, l-1} V_{k}^{I-1}+\lambda_{/ l} V_{k}^{I}+\lambda_{l, l+1} V_{k}^{I+1} \\
& =\frac{\sigma^{2}\left(v_{l}\right)}{2}\left[\frac{V_{k}^{I-1}-2 V_{k}^{I}+V_{k}^{I-1}}{\delta_{v}^{2}}\right]+\mu\left(v_{l}\right)\left[\frac{V_{k}^{I+1}-V_{k}^{I-1}}{2 \delta_{v}}\right] \\
& \rightarrow \frac{1}{2} \sigma^{2}\left(v_{l}\right) \frac{\partial^{2} V}{\partial v^{2}}+\mu\left(v_{l}\right) \frac{\partial V}{\partial v}, \quad \text { as } \delta_{v} \downarrow 0
\end{aligned}
$$

- Analogous result for other terms as $\delta_{x} \downarrow 0$
- Hence weak convergence: $\left(\tilde{X}^{(N)}, v_{\alpha(t)}\right) \Longrightarrow\left(X_{t}, v_{t}\right)$, from which expected values (prices) converge to true values


## Weak Convergence

## Proposition

(Proposition 3) For each fixed $m_{0}$ and $N$, let $\left[x_{1}, x_{N}\right]$ and $\left[v_{1}, v_{m_{0}}\right]$ be the truncation domains ${ }^{6}$ for the processes $\tilde{X}_{t}^{(N)}$ and $v_{\alpha(t)}^{m_{0}} \equiv v_{\alpha(t)}$ respectively. For each $m_{0}$ and $N$, choose $\mathbf{\Lambda}=\left(\lambda_{i j}\right)_{m_{0} \times m_{0}}$ and $\mathbf{G}_{I}=\left(q_{i j}^{\prime}\right)_{N \times N}$ for $I=1, \ldots, m_{0}$ as in the paper. Then

$$
\left(\tilde{X}_{t}^{(N)}, v_{\alpha(t)}^{m_{0}}\right) \Longrightarrow\left(X_{t}, v_{t}\right), \quad \text { as } \quad m_{0}, N \rightarrow \infty
$$

Here " $\Longrightarrow$ " indicates weak convergence of the regime-switching CTMC approximation to the true process.

[^1]
## Convergence Order

- Li and Zhang (2016) ${ }^{7}$ consider an error estimate of the option value using the Markov chain approximation of Mijatovic and Pistorius (2013) ${ }^{8}$.
- Using the spectral analysis, they show that for call/put-type payoffs, the convergence is of second order, while for digital-type payoffs, the convergence is only of first order in general.
- It is expected that the same convergence type would hold for the model considered in this paper. It would be very interesting to carry this out. We leave this as an interesting project for future studies.

[^2]
## Transform to One-dimensional CTMC

- Process $\left(\tilde{X}^{(N)}, v_{\alpha(t)}\right)$ defines a RS-CTMC
- Next apply theorem of Song et al $(2016)^{9}$ to convert to a 1-D CTMC, $\left\{Y_{t}, t \geq 0\right\}$, on $\mathcal{S}_{Y}:=\left\{1,2, \ldots, N \cdot m_{0}\right\}$
- First find a bijection between state space $\mathcal{S}_{X} \times \mathcal{M}$ of $\left(\tilde{X}^{(N)}, v_{\alpha(t)}\right)$ to $\mathcal{S}_{Y}$ of $Y_{t}$
- Define the mapping $\phi: \mathcal{S}_{X} \times \mathcal{M} \rightarrow \mathcal{S}_{Y}$ by

$$
\phi\left(x_{k}, I\right)=(I-1) N+k, \quad 1 \leq I \leq m_{0}, 1 \leq k \leq N
$$

- Inverse $\phi^{-1}: \mathcal{S}_{Y} \rightarrow \mathcal{S}_{X} \times \mathcal{M}$ by

$$
\phi^{-1}(n)=\left(x_{k}, l\right), \quad \text { for } n \in \mathcal{S}_{Y}
$$

where $k$ is the unique integer satisfying $n=(I-1) N+k$ for some $I \in\left\{1,2, \ldots, m_{0}\right\}$.
${ }^{9}$ Song, Y., Cai, N. and Kou, S., 2016. A Unified Framework for Options Pricing under Regime Switching Models.

## Transform to One-dimensional CTMC

Theorem
(Song et al (2016)) Define the $N \cdot m_{0} \times N \cdot m_{0}$ rate matrix

$$
\mathbf{G}=\left(\begin{array}{cccc}
\lambda_{11} \mathbf{l}_{N}+\mathbf{G}_{1} & \lambda_{12} \mathbf{I}_{N} & \cdots & \lambda_{1 m_{0}} \mathbf{I}_{N} \\
\lambda_{21} \mathbf{l}_{N} & \lambda_{22} \mathbf{l}_{N}+\mathbf{G}_{2} & \cdots & \lambda_{2 m_{0}} \mathbf{l}_{N} \\
\vdots & \vdots & \ddots & \vdots \\
\lambda_{m_{0}} \mathbf{I}_{N} & \lambda_{m_{0}} \mathbf{l}_{N} & \cdots & \lambda_{m_{0} m_{0}} \mathbf{I}_{N}+\mathbf{G}_{m_{0}}
\end{array}\right),
$$

where $\mathbf{I}_{N}$ is the $N \times N$ identity matrix, $\mathbf{G}_{/}=\left(q_{k j}^{\prime}\right)_{N \times N}$, and $\boldsymbol{\Lambda}=\left(\lambda_{k, j}\right)_{m_{0} \times m_{0}}$. Then we have

$$
\begin{aligned}
& \mathbb{E}\left[\Psi\left(\tilde{X}^{(N)}, \alpha\right) \mid \alpha(0)=i, \tilde{X}_{0}^{(N)}=x_{k}\right] \\
& =\mathbb{E}\left[\Psi \circ \phi^{-1}(Y) \mid Y_{0}=(i-1) N+k\right],
\end{aligned}
$$

for any path-dependent payoff function $\Psi$. Here we have defined $\tilde{X}^{(N)}:=\left(\tilde{X}_{t}^{(N)}\right)_{0 \leq t \leq T}, \alpha:=(\alpha(t))_{0 \leq t \leq T}$, and $Y:=\left(Y_{t}\right)_{0 \leq t \leq T}$.

## European Options

- Vanilla option prices for the underlying $S_{T}$ can now be approximated with respect to

$$
\begin{equation*}
\tilde{S}_{T}^{(N)}:=g^{-1}\left(\tilde{X}_{T}^{(N)}+\rho f\left(v_{\alpha(T)}\right)\right) \tag{3}
\end{equation*}
$$

- For example

$$
\begin{aligned}
& \mathbb{E}\left[e^{-r T}\left(S_{T}-K\right)^{+} \mid v_{0}, S_{0}\right] \\
& \approx \mathbb{E}\left[e^{-r T}\left(\tilde{S}_{T}^{(N)}-K\right)^{+} \mid \alpha(0)=i, \tilde{X}_{0}^{(N)}=x_{k}\right] \\
& =e^{-r T} \cdot \mathbf{e}_{i, x_{k}} \cdot \exp (\mathbf{G} T) \cdot \mathbf{H}^{(1)}
\end{aligned}
$$

where $\mathbf{e}_{i, x_{k}}$ is a $1 \times N m_{0}$ vector with all entries equal to 0 except that the $(i-1) N+k$ entry is equal to 1 , and $\mathbf{H}^{(1)}$ is an $N m_{0} \times 1$ vector with

$$
H_{(I-1) N+j}^{(1)}= \begin{cases}\left(g^{-1}\left(\tilde{x}_{j}+\rho f\left(v_{l}\right)\right)-K\right)^{+} & \text {for a call, } \\ \left(K-g^{-1}\left(\tilde{x}_{j}+\rho f\left(v_{l}\right)\right)\right)^{+} & \text {for a put. }\end{cases}
$$

- By the continuity of $g^{-1}(\cdot)$, it follows from Proposition 3 and the continuous mapping theorem that

$$
\tilde{S}_{T}^{(N)} \Longrightarrow S_{T}, \quad \text { as } \quad m_{0}, N \rightarrow \infty
$$

- It then follows that $\mathbb{E}\left[H\left(\tilde{S}_{T}^{(N)}\right)\right] \rightarrow \mathbb{E}\left[H\left(S_{T}\right)\right]$ for any bounded payoff $H(\cdot)$ which is continuous on $C \subset[0, \infty)$ such that $\mathbb{Q}\left[S_{T} \in C\right]=1$.
- Assuming that $\mathbb{E}\left[H\left(S_{T}\right)\right]<\infty$, for any $\epsilon>0$ we can choose $\theta>0$ such that $\mathbb{E}\left[H\left(S_{T}\right)-H\left(S_{T}\right) \mathbb{1}_{\left\{S_{T \leq \theta\}}\right.}\right]<\epsilon$, and

$$
\mathbb{E}\left[H\left(\tilde{S}_{T}^{(N)}\right) \mathbb{1}_{\left\{S_{T}^{(N)} \leq \theta\right\}}\right] \rightarrow \mathbb{E}\left[H\left(S_{T}\right) \mathbb{1}_{\left\{S_{T} \leq \theta\right\}}\right]
$$

- Hence, the Markov chain value approximation will converge for any finitely valued European option.


## American and Barrier Options

- Define transition density $\mathbf{P}_{Y}(\Delta):=\exp (\mathbf{G} \Delta)$ of $Y_{\Delta}$.
- Bermudan value recursion for $\mathcal{V}^{\operatorname{Ber}}\left(\tilde{X}_{0}^{(N)}, \alpha_{0}, K\right)=\mathcal{V}_{0}(n)$ :

$$
\left\{\begin{array}{l}
\mathcal{V}_{M}=\mathbf{H}^{(\mathbf{1})} \\
\mathcal{V}_{m}=\max \left\{e^{-r \Delta} \mathbf{P}_{Y}(\Delta) \mathcal{V}_{m+1}, \mathbf{H}^{(\mathbf{1})}\right\}, \quad m=M-1, \ldots, 0
\end{array}\right.
$$

- Barrier option with knock-out barrier $B \geq 0$ : define the indicator vector $\mathbf{1}_{B}$, where for each $n=(I-1) N+k \in \mathcal{S}_{Y}$,

$$
\mathbf{1}_{B}(n)= \begin{cases}\mathbb{1}\left\{g(B) \leq x_{k}+\rho f\left(v_{l}\right)\right\}, & \text { down-and-out } \\ \mathbb{1}\left\{g(B) \geq x_{k}+\rho f\left(v_{l}\right)\right\}, & \text { up-and-out },\end{cases}
$$

- Recursion to find $\mathcal{V}^{\operatorname{Bar}}\left(\tilde{X}_{0}^{(N)}, \alpha_{0}, B, K\right)=\mathcal{V}_{0}(n)$

$$
\left\{\begin{array}{l}
\mathcal{V}_{M}=\mathbf{H}^{(\mathbf{1})} \circ \mathbf{1}_{B} \\
\mathcal{V}_{m}=e^{-r \Delta} \mathbf{P}_{Y}(\Delta) \mathcal{V}_{m+1} \circ \mathbf{1}_{B}, \quad m=M-1, \ldots, 0
\end{array}\right.
$$

## Asian Options (Laplace transform)

- For discretely monitored Asian option

$$
\begin{aligned}
\sum_{m=0}^{M} \tilde{S}_{t_{m}}^{(N)} & =\sum_{m=0}^{M} g^{-1}\left(\tilde{X}_{t_{m}}^{(N)}+\rho f\left(v_{t_{m}}\right)\right) \\
& =\sum_{m=0}^{M} \zeta \circ \phi^{-1}\left(Y_{t_{m}}\right)=\sum_{m=0}^{M} h\left(Y_{t_{m}}\right):=\tilde{B}_{M}^{(N)}
\end{aligned}
$$

- Let $v_{d}(M, k)=\mathbb{E}_{i, x_{k}}\left[\left(k-\tilde{B}_{M}^{(N)}\right)^{+}\right]$, then

$$
V_{d}(M, K)=\frac{e^{-r T}}{M+1} v_{d}(M,(M+1) K)
$$

which is found upon inverting the Laplace transform:

$$
\int_{0}^{\infty} e^{-\theta k} v_{d}(M, k) d k=\frac{\mathbf{e}_{i, x_{k}} \cdot\left(e^{-\theta \mathbf{D}} \mathbf{P}(\Delta)\right)^{M} e^{-\theta \mathbf{D}} \cdot \mathbf{1}}{\theta^{2}}
$$

## Occupation Time Derivatives

- Define continuous and discrete occupation time for barrier $L$ :

$$
\tau_{T}(L):=\int_{0}^{T} 1\left\{S_{u} \leq L\right\} d u, \quad \tau_{M}(L):=\sum_{m=0}^{M} 1\left\{S_{t_{m}} \leq L\right\}
$$

- Value of proportional payoff (with $\rho \geq 0$ ):

$$
C_{c}(\kappa, T)=e^{-r T} \mathbb{E}\left[e^{-\rho \tau_{T}(L)}\left(S_{T}-e^{-\kappa}\right)^{+}\right]
$$

- Closed-form approximation of Laplace Transform:

$$
\begin{equation*}
\int_{-\infty}^{\infty} e^{-\phi \kappa} C_{c}(\kappa, T) d \kappa \approx \frac{e^{-r T}}{\phi(1+\phi)} \mathbf{e}_{i, x_{k}} \cdot e^{(\mathbf{G}-\tilde{\mathbf{D}}) T} \tilde{V}_{\phi}(\mathbf{y}) \tag{4}
\end{equation*}
$$

- (Note): $\tilde{V}_{\phi}(\cdot):=\left(\zeta \circ \phi^{-1}(\cdot)\right)^{1+\phi}, \mathbf{y}:=\left(1,2, \ldots, N \cdot m_{0}\right)^{T}$, and $\tilde{\mathbf{D}}=\left(\tilde{d}_{n n}\right)_{N m_{0} \times N m_{0}}$ is a diagonal matrix $\tilde{d}_{n n}=\tilde{H}(n)=\rho \cdot \mathbb{1}\left\{\zeta \circ \phi^{-1}(n) \leq L\right\}$ for $n \in \mathcal{S}_{Y}$
- By the continuity of $g^{-1}(\cdot)$, it follows from Proposition 3 and the continuous mapping theorem that

$$
\tilde{S}_{T}^{(N)} \Longrightarrow S_{T}, \quad \text { as } \quad m_{0}, N \rightarrow \infty
$$

- Again by the continuous mapping theorem we have $h\left(\tilde{S}_{t_{m}}^{(N)}\right) \Longrightarrow h\left(S_{t_{m}}\right)$, for any continuous function $h$.
- Hence the Theorem 9 of Song et al. (2013) ${ }^{10}$ implies that value of discretely monitored barrier/Bermudan/Asian options written on $h\left(\tilde{S}_{t_{m}}^{(N)}\right)$ will converge to those written on $h\left(S_{t_{m}}\right)$.
${ }^{10}$ Song, Q., Yin, G. and Zhang, Q., 2013. Weak convergence methods for approximation of the evaluation of path-dependent functionals. SIAM Journal on Control and Optimization, 51(5), pp.4189-4210.


## SABR

- Recall the classical SABR model of Hagan et al (2002) ${ }^{11}$ :

$$
\left\{\begin{array}{l}
d S_{t}=v_{t} S_{t}^{\beta} d W_{t}^{(1)} \\
d v_{t}=\alpha v_{t} d W_{t}^{(2)}
\end{array}\right.
$$

- Combines CEV local volatility $S_{t}^{\beta}$ with GBM volatility process
- Auxiliary process:

$$
\tilde{X}_{t}:=g\left(\tilde{S}_{t}\right)-\rho f\left(v_{\alpha(t)}\right)=\left(\tilde{S}_{t}\right)^{1-\beta} /(1-\beta)-\rho v_{\alpha(t)} / \alpha
$$

- Dynamics

$$
d \tilde{X}_{t}=\left(-\frac{\beta}{2(1-\beta)} \frac{v_{\alpha(t)}^{2}}{\left(\tilde{X}_{t}+\rho v_{\alpha(t)} / \alpha\right)}\right) d t+\sqrt{1-\rho^{2}} v_{\alpha(t)} d W_{t}^{*}
$$

${ }^{11}$ Hagan, P.S., Kumar, D., Lesniewski, A.S. and Woodward, D.E., 2002. Managing smile risk. The Best of Wilmott, 1, pp.249-296.

## Extensions

- Given a local volatility component $\Gamma\left(S_{t}\right)$, we can "mix-and-match" our favorite variance processes to improve calibration in targeted markets
- E.g. variations of SABR include Heston-SABR, $\lambda$-SABR, etc., and many more variance dynamics can be applied
- Moreover, as long as the Lamperti transform $g\left(S_{t}\right)$ can be derived, monotonicity guarantees the existence of $g^{-1}(\cdot)$
- Hence, even if $g^{-1}(\cdot)$ is not available in closed form, we can easily invert numerically for the required values along our grid
- E.g. Hyp-Hyp model of Jackel and Kahl (2007) ${ }^{12}$

[^3]
## SABR Numerics (European): Case $\rho=0$

|  |  |  |  |  | K |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\Delta t$ | 0.02 | 0.04 | 0.05 | 0.06 | 0.08 | 0.10 | CPU(sec.) |
| Euler | 1/400 | 0.0472 | 0.0429 | 0.0409 | 0.0389 | 0.0352 | 0.0318 | 49.4 |
|  | 1/800 | 0.0463 | 0.0420 | 0.0399 | 0.0380 | 0.0343 | 0.0309 | 99.1 |
|  | 1/1600 | 0.0453 | 0.0411 | 0.0391 | 0.0372 | 0.0336 | 0.0303 | 194.0 |
| Low-bias | 1/4 | 0.0461 | 0.0419 | 0.0399 | 0.0379 | 0.0343 | 0.0310 | 78.4 |
|  | 1/8 | 0.0460 | 0.0418 | 0.0398 | 0.0378 | 0.0342 | 0.0308 | 175.8 |
| Exact Sim | - | 0.0457 | 0.0416 | 0.0396 | 0.0377 | 0.0341 | 0.0308 | 98.3 |
| FDM | - | 0.0456 | 0.0414 | 0.0394 | 0.0375 | 0.0339 | 0.0306 | - |
| CTMC | - | 0.0456 | 0.0414 | 0.0394 | 0.0375 | 0.0339 | 0.0306 | 1.8 |

Table: European call options. Parameters:
$S_{0}=0.05, T=1.0, \rho=0, \beta=0.30, \alpha=0.60, v_{0}=0.40$. The Euler, Low-bias, Exact Sim, and FDM rows are reported in Song (2013): "Essays on computational methods in financial engineering (Doctoral dissertation)". Exact simulation results are obtained using 100, 000 sample paths.

## SABR Numerics (European): Case $\rho \neq 0$

| $K$ | Exact simulation | StdErr | 95 Cl | Expansion | CTMC |
| ---: | :---: | :---: | :---: | :---: | :---: |
| 0.045 | 0.008889 | $1.30 \mathrm{E}-06$ | $[0.008787,0.008792]$ | 0.0088788 | 0.008787 |
| 0.046 | 0.008204 | $1.34 \mathrm{E}-06$ | $[0.008201,0.008206]$ | 0.008202 | 0.008201 |
| 0.047 | 0.007644 | $1.37 \mathrm{E}-06$ | $[0.007642,0.007647]$ | 0.007643 | 0.007642 |
| 0.048 | 0.007111 | $1.39 \mathrm{E}-06$ | $[0.007109,0.007114]$ | 0.007110 | 0.007109 |
| 0.049 | 0.006605 | $1.41 \mathrm{E}-06$ | $[0.006602,0.006608]$ | 0.006603 | 0.006603 |
| 0.050 | 0.006124 | $1.43 \mathrm{E}-06$ | $[0.006121,0.006127]$ | 0.006123 | 0.006122 |
| 0.051 | 0.005669 | $1.44 \mathrm{E}-06$ | $[0.005667,0.005672]$ | 0.005668 | 0.005667 |
| 0.052 | 0.005240 | $1.45 \mathrm{E}-06$ | $[0.005237,0.005243]$ | 0.005238 | 0.005237 |
| 0.053 | 0.004835 | $1.45 \mathrm{E}-06$ | $[0.004832,0.004838]$ | 0.004833 | 0.004833 |
| 0.054 | 0.004454 | $1.44 \mathrm{E}-06$ | $[0.004451,0.004457]$ | 0.004453 | 0.0004452 |
| 0.055 | 0.004096 | $1.44 \mathrm{E}-06$ | $[0.004094,0.004099]$ | 0.004095 | 0.004094 |

Table: European call option under SABR model. Parameters:
$S_{0}=0.05, T=1, \rho=-0.25, \beta=0.55, \alpha=0.03, v_{0}=0.08, r=0$. The expansion column is obtained using expansion formulas in Hagan et al (2002) and Oblój (2008). Exact simulation results obtained using $10,240,000$ sample paths.

## SABR Numerics (American and Barrier)

|  | $K$ | 1.00 | 1.02 | 1.04 | 1.06 | 1.08 | 1.10 | 1.12 | 1.14 | 1.16 | 1.18 | 1.20 |
| :--- | ---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| American | LSM | 0.0424 | 0.0494 | 0.0574 | 0.0659 | 0.0749 | 0.0852 | 0.0959 | 0.1074 | 0.1199 | 0.1326 | 0.1459 |
|  | CTMC | 0.0424 | 0.0494 | 0.0572 | 0.0658 | 0.0751 | 0.0851 | 0.0959 | 0.1074 | 0.1196 | 0.1326 | 0.1461 |
| Barrier | MC | 0.0394 | 0.0463 | 0.0541 | 0.0624 | 0.0715 | 0.0814 | 0.0921 | 0.1034 | 0.1155 | 0.1283 | 0.1417 |
|  | CTMC | 0.0396 | 0.0465 | 0.0542 | 0.0626 | 0.0717 | 0.0816 | 0.0923 | 0.1036 | 0.1157 | 0.1285 | 0.1419 |

Table: American and down-and-out barrier put options under the SABR model. Parameters:
$S_{0}=1.10, T=1, \rho=-0.40, \beta=0.70, \alpha=0.08, v_{0}=0.20, r=0.0$.
LSM is computed using $10^{7}$ sample paths. Barrier option: $L=0.6$ with $M=250$ monitoring dates.

## SABR Numerics (Asian)

| $M$ | $K$ | 0.90 | 0.95 | 1.00 | 1.05 | 1.10 |
| :---: | ---: | :---: | :---: | :---: | :---: | :---: |
| 250 | MC | 0.0059 | 0.0156 | 0.0345 | 0.0647 | 0.1048 |
| 250 | CTMC | 0.0058 | 0.0154 | 0.0344 | 0.0646 | 0.1047 |
| 50 | MC | 0.0058 | 0.0155 | 0.0344 | 0.0646 | 0.1048 |
| 50 | CTMC | 0.0057 | 0.0153 | 0.0342 | 0.0644 | 0.1046 |
| 12 | MC | 0.0056 | 0.0150 | 0.0338 | 0.0641 | 0.1045 |
| 12 | CTMC | 0.0055 | 0.0149 | 0.0337 | 0.0640 | 0.1044 |

Table: Discretely monitored arithmetic Asian put options under the SABR model. Parameters:
$S_{0}=1, r=0, T=1, \beta=0.5, \alpha=0.3, v_{0}=0.15, \rho=-0.5$.

## Heston-SABR Numerics (Euro, American)

| $K / S_{0}$ | $70 \%$ | $80 \%$ | $90 \%$ | $100 \%$ | $110 \%$ | $120 \%$ | $130 \%$ |
| ---: | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| MS-Eur Call | 3.2066 | 2.2426 | 1.3108 | 0.5395 | 0.1276 | 0.0122 | 0.0003 |
| CTMC-Eur Call | 3.2069 | 2.2405 | 1.3101 | 0.5457 | 0.1281 | 0.0138 | 0.0007 |
| LSM-Amer Put | 0.0002 | 0.0042 | 0.0472 | 0.2802 | 0.9937 | 1.9930 | 2.9922 |
| CTMC-Amer Put | 0.0002 | 0.0044 | 0.0473 | 0.2813 | 0.9999 | 1.9999 | 2.9999 |

Table: Options under Heston-SABR. Parameters: $S_{0}=10, T=1.0, \rho=$ $-0.75, \alpha=0.15, v_{0}=0.04, \theta=0.035, \eta=4, \beta=0.70$, interest rate $r=0.03$. LSM is computed using $10^{7}$ sample paths.

## Quadratic SLV Numerics (Euro, Barrier, American, Asian)

|  | $K$ | 8.0 | 9.0 | 9.5 | 10.0 | 10.5 | 11.0 | 12.0 |
| :--- | ---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| European Call | MC | 2.0003 | 1.0032 | 0.5319 | 0.1761 | 0.0251 | 0.0010 | 0.0000 |
|  | CTMC | 2.0002 | 1.0035 | 0.5327 | 0.1759 | 0.0262 | 0.0017 | 0.0000 |
| Down-Out-Call | MC | 1.6281 | 0.8791 | 0.5046 | 0.1745 | 0.0251 | 0.0010 | 0.0000 |
|  | CTMC | 1.6337 | 0.8813 | 0.5051 | 0.1742 | 0.0251 | 0.0011 | 0.0000 |
| American Put | LSM | 0.0000 | 0.0028 | 0.0315 | 0.1757 | 0.5250 | 1.0010 | 2.0000 |
|  | CTMC | 0.0000 | 0.0033 | 0.0325 | 0.1757 | 0.5260 | 1.0015 | 1.9999 |
| Asian Put | MC | 0.0000 | 0.0000 | 0.0032 | 0.1014 | 0.5018 | 1.0002 | 2.0002 |
|  | CTMC | 0.0000 | 0.0000 | 0.0039 | 0.1032 | 0.5017 | 0.9989 | 1.9991 |

Table: Quadratic SLV model: $r=0, S_{0}=10, T=0.5, v_{0}=0.035, \eta=$ $4, \theta=0.03, \rho=-0.7, a=0.02, b=0.05, c=1$. Down-and-out barrier $B=9.5$, and $M=500$. Asian put with $M=12$.

## Thank You

Q \& A


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[^1]:    ${ }^{6}$ We have the freedom to choose $x_{1}, x_{N}, v_{1}, v_{m_{0}}$, and we will choose them so that the domain of $\left(X_{t}, v_{t}\right)$ is covered sufficiently.

[^2]:    ${ }^{7}$ Li, L. and Zhang, G., 2016. Option Pricing in Some Non-Levy Jump Models. SIAM Journal on Scientific Computing, 38(4), pp.B539-B569.
    ${ }^{8}$ Mijatovic, A. and Pistorius, M., 2013. Continuously monitored barrier options under Markov processes. Mathematical Finance, 23(1), pp-1-38 $\equiv$

[^3]:    ${ }^{12}$ Jackel, P. and Kahl, C., 2008. Hyp hyp hooray. Wilmott Magazine, 34, pp.70-81.

